



## New Opportunities in Predictive and Pro-active Traffic Safety Evaluation and Management in the Era of Smart Cities

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Vision Zero Town + Gown Research on the Road 06/10/2021

#### **Safety Facts**



- Each year, there are about 1.35 million road traffic deaths and 50 million injured worldwide.
- Road crashes are expected to rise to the 7<sup>th</sup> leading cause of death by the year 2030.











## **Surrogate Safety Measures**



- Surrogate Safety Measures (SSMs):
  - Used to identify traffic conflicts or "near-misses".
  - Extracted from vehicle trajectories.

Traditionally, the collection of vehicle trajectories is relatively difficult or time consuming.

• Traffic safety risk can thus be reflected by the identified traffic conflicts.



## **Emerging Technologies**



 In the era of smart cities, the collection of vehicle trajectories becomes easier due to various emerging technologies.



**Connected Vehicles** 



Laureshyn, A., & Varhelyi, A. (2018). The Swedish Traffic Conflict Technique: observer's manual.;

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Drones

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https://wydotcvp.wyoroad.info/: http://myphonefactor.in/2012/04/sensors-used-in-a-smartphone/: https://www.tomstechtime.com/post/2019/01/12/whats-the-best-drone-video-editing-software



## **USDOT NYC Connected Vehicle Pilot Deployment**



New York City is one of three **Connected Vehicle (CV) pilot deployment** sites selected by USDOT to demonstrate the benefits of this new Connected Vehicle technology.

The CV technology is a new tool to help NYC reach its **Vision Zero** goals to eliminate traffic related deaths and reduce crash related injuries and damage to both the vehicles and infrastructure.



#### 3000+ vehicles



#### 450+ Roadside Units



**14 Mobility and Safety Applications** (include one that supports people with visual disabilities)





NYC Connected Vehicle pilot deployment Website: https://cvp.nyc

## **USDOT Other Connected Vehicle Pilot Deployment**



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#### Wyoming Connected Vehicle Pilot

- Objective: improving safety and travel reliability on i-80 in Wyoming
- Scope:
  - 400 instrumented vehicles
  - 75 roadside units



#### Tampa Connected Vehicle Pilot

- Objective: transform the experience of drivers, transit riders and pedestrians in downtown Tampa by preventing crashes, enhancing traffic flow, improving transit trip times and reducing emissions of greenhouse gases.
- Scope:
  - Over 1000 privately owned vehicles
  - I0 buses
  - 8 streetcars
  - 46 roadside units



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https://wydotcvp.wyoroad.info/; https://theacvpilot.com/;

## Video-Based Safety Evaluation (Work funded by AIG)

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- Goals: Advance data-driven traffic analytics to enhance Global Resilience
- Objectives:
  - Propose a novel approach for examining traffic safety performance at intersections
  - Quantify traffic conflicts using developed "surrogate" safety measures
  - Develop automatic data acquisition, analysis and modeling approaches based on computer vision techniques



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8



Fig. 1: Original video recording Fig. 2: Extract feature points using Kanade-Lucas-Tomasi (KLT) Feature Tracker

Fig. 3: Group feature points using Dirchlet process mixture algorithm Fig. 4: Convert coordinates to relative distances

NYU UrbanMITS lab (in collaboration with AIG), Development of A Comprehensive Experimental and Theoretical Methodology for Video-based Safety Assessment

#### **Video-Based Safety Evaluation**





#### Estimated Surrogate Events based on Automatic Tracking Results



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9

#### **Proactive Safety Evaluation & Monitoring**









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Traffic risk can be quantified.





Suitable for proactive safety monitoring.

- Detect potential safetyrelated anomalies that may cause high traffic risk.
- Provide intervention.

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## **Characteristics of Surrogate Events**

#### **Surrogate Events**

#### Frequent

 Large amount of conflict data can be collected in a relatively short period of time (e.g., hours or days)

#### Detailed temporal and spatial information

e.g., accurate at the second and the lane level

How to represent safety risk? What method should we use to capture these characteristics?

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#### Crashes

#### Rare events

• Often take months or years to accumulate.

#### Rough location and time information

e.g., at the intersection level





## **Functional Data Analysis**

- A typical example
  - X axis: 12 months from January to December
  - Y axis: mean temperature
  - Each curve: one weather station in Canada

#### Formally, FDA is

- A branch of statistics that analyzes data providing information about curves, surfaces or anything else varying over a continuum.
- The physical continuum over which these functions are defined is often time.







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## **Functional Data Analysis for Proactive Safety** Monitoring



- Analogously, for signalized intersections with pre-timed signal mode.
  - Model time series of traffic risk to detect green intervals with safety-related anomalies.



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#### Safety Risk:

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Number of surrogate events / number of vehicles (unit: second)

#### **Safety-related anomalies:**

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- **Type I**: vehicles commit dangerous or illegal lane changing behaviors.
- Type 2: vehicles slow down or stop unexpectedly or abruptly.
- **Type 3**: vehicles blocked by other vehicles in the crossing directions.

## Key Steps in Functional Data Analysis



- Two key steps of using FDA for proactive safety monitoring:
  - Step I: Data representation Functional data smoothing
    - Convert from discrete observations to continuous functions for further mathematical analysis.
  - Step 2: Extract functional outlier detection measures from the estimated functional curves for outlier detection.



## **Data Collection**



Location: Flatbush Avenue & Tillary Street

- Study movement: the northbound throughput (NBT) direction.
- Time: Morning peak period (6 AM to 8 AM)









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## **Data Collection**



#### Extraction of vehicle trajectories

- Anonymous vehicle trajectories were extracted from the recorded UAV videos by a company called Data From Sky.
  - Longitude & latitude, speed, acceleration, and vehicle type

Time	Vehicle ID	Vehicle Type	Latitude	Longitude	Speed	Acceleration (longitudinal)	Acceleration (lateral)
0.1	1	Car	40.695942	-73.984531	12.5543	-0.0181	0.0647
0.2	1	Car	40.695941	-73.984527	12.5437	-0.0427	0.0831
0.3	1	Car	40.695941	-73.984523	12.5241	-0.0675	0.0998
0.4	1	Car	40.695941	-73.984519	12.4954	-0.0961	0.1202
0.5	1	Car	40.695941	-73.984515	12.5055	-0.0578	0.0889
0.6	1	Car	40.695941	-73.98451	12.4794	-0.085	0.1084
0.7	1	Car	40.69594	-73.984506	12.4443	-0.1091	0.1134
0.8	1	Car	40.69594	-73.984502	12.4024	-0.1223	0.1166
0.9	1	Car	40.69594	-73.984498	12.3571	-0.1298	0.1112
1	1	Car	40.69594	-73.984494	12.3109	-0.1268	0.1004



16



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#### **Findings:**

- Distinct separation between outliers and non-outliers.
- Peaks at the beginning of the green interval.
  - Caused by early acceleration of vehicles in queue before the acceleration of the vehicles in front.
  - This pattern cannot be revealed if traffic risk is aggregated into summary statistics of any kind.



# **Results: Smoothing Functional Curves**





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## **Results: Receiver Operating Characteristics (ROC) & Precision-Recall (PR) curves**



#### **Findings**

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- Overall, ROC curves of all the functional outlier detection measures are above the random classifier line.
- PR curves show similar patterns.

measures are compared.

----- Random classifier



## **Results: Area Under the Curve (AUC)**



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- Findings:
  - Best outlier detection measures is consistent for both ROC and PR AUC values.
    - Consistent between ROC-AUC and PR-AUC
  - Good separation between normal and abnomal cases are achieved.

	FMD	MD	RP	RPD	RT	FSD	KFSD 🗸	Bivariate Score Depth	Bivariate Score Density
AUC-ROC	0.70	0.82	0.79	0.82	0.77	0.77	0.85 🗸	0.65	0.72
AUC-PR	0.45	0.79	0.76	0.71	0.57	0.77	0.80 🗸	0.42	0.68



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## **Practical Implementation**

**Step I:** Collect real time data feed





**Step 3**: Calculate outlier detection measure Step 4: NYU

Identify anomalies based on a preset threshold.





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# Reservoir of historically identified normal risk functions



20

## **Our Paper**



- Yang, D., Ozbay, K., Xie, K., Yang, H., Zuo, F., Sha, D., 2021. Proactive safety monitoring: A functional approach to detect safety-related anomalies using unmanned aerial vehicle video data. Transportation Research Part C: Emerging Technologies 127, 103130.
  - DOI: <u>https://doi.org/10.1016/j.trc.2021.103130</u>



Transportation Research Part C: Emerging Technologies

Volume 127, June 2021, 103130



Proactive safety monitoring: A functional approach to detect safety-related anomalies using unmanned aerial vehicle video data

21

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## What About Crash Data?



- Only surrogate events are used above to quantify traffic safety risk.
- However, both crash data and surrogate events can provide information regarding traffic safety conditions.
  - Most of the studies in the literature used only one of these.
  - However, this may lead to inaccurate safety estimates, which accordingly may lead to incorrect decision making and waste of sources.
- It is important to combine both of these together in a robust way.



Tarko, A., 2018. Surrogate measures of safety. Safe mobility: Challenges, methodology and solutions. Emerald Publishing Limited, 383-405.

## Integration of Crashes and Safety Risk for Safety Analysis



- Integrating both crash data and safety risk may result in more comprehensively evaluation of traffic safety.
- Methods we proposed:



#### **Our Research**

- Yang, D., Xie, K., Ozbay, K., Yang, H., Budnick, N., 2019. Modeling of time-dependent safety performance using anonymized and aggregated smartphone-based dangerous driving event data. Accident Analysis and Prevention 132, 105286.
- Yang, D., Xie, K., Ozbay, K., Zhao, Z., Yang, H., 2021. Copula-based joint modeling of crash count and conflict risk measures with accommodation of mixed count-continuous margins. Analytic Methods in Accident Research 31, 100162.
- Yang, D., Xie, K., Ozbay, K., Yang, H., 2021. Fusing crash data and surrogate safety measures for safety assessment: Development of a structural equation model with conditional autoregressive spatial effect and random parameters. Accident Analysis and Prevention 152, 105971.



24



Accident Analysis & Prevention Volume 132, November 2019, 105286

Modeling of time-dependent safety performance using anonymized and aggregated smartphonebased dangerous driving event data

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Analytic Methods in Accident Research Volume 31, September 2021, 100162



Copula-based joint modeling of crash count and conflict risk measures with accommodation of mixed count-continuous margins

Di Yang Ӓ 🖾, Kun Xie 🖾, Kaan Ozbay 🖾, Zifeng Zhao 🖾, Hong Yang 🖾



Accident Analysis & Prevention Volume 152, March 2021, 105971



Fusing crash data and surrogate safety measures for safety assessment: Development of a structural equation model with conditional autoregressive spatial effect and random parameters

## The Future of Proactive Safety Management

- Other potential approaches for integrating surrogate events and crashes
- Other potential use cases of functional approach in transportation safety

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- Facilitate proactive safety management for signalized intersections
- Calibration of microsimulation models for safety evaluation
- Signal timing optimization accounting for safety
- Ramp-metering control strategy development accounting for safety

Comprehensive Evaluation of Feedback-Based Freeway Ramp-Metering Strategy by Using Microscopic Simulation: Taking Ramp Queues into Account

Kaan Ozbay, Ilgin Yasar, Pushkin Kachroo

First Published January 1, 2004 Research Article https://doi.org/10.3141/1867-11



Accident Analysis & Prevention Volume 38, Issue 2, March 2006, Pages 279-288

Quantifying effects of ramp metering on freeway safety 🖈

Chris Lee<sup>a</sup>, Bruce Hellinga<sup>b</sup> A ⊠, Kaan Ozbay<sup>c</sup>

25



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